

Exam I MTH 512, Fall 2018

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QUESTION 1. Let $B = \{(1, -1, -1), (1, 0, -1), (1, -1, 0)\}$ be a basis for R^3 and $B' = \{(1, -1), (-1, 2)\}$ be a basis for R^2 . Let $T : R^3 \rightarrow R^2$ be a linear transformation over R such that $T(1, -1, -1) = (1, -1)$, $T(1, 0, -1) = (-1, 1)$, $T(1, -1, 0) = (1, 0)$.

(i) Find the matrix representation of T with respect to B and B' , i.e. $M_{B,B'}$.

Using class notes $Q = \begin{bmatrix} 1 & 1 & 1 \\ -1 & 0 & -1 \\ -1 & -1 & 0 \end{bmatrix}$, $W = \begin{bmatrix} 1 & -1 \\ -1 & 2 \end{bmatrix}$. Let M be the standard matrix representation.

We know $M_{B,B'} = W^{-1}MQ$. Now, reading class notes, we know that $T(1, -1, -1)$ is the first column of MQ , $T(1, 0, -1)$ is the second column of MQ , and $T(1, -1, 0)$ is the third column of MQ . Hence staring at the question $MQ = \begin{bmatrix} 1 & -1 & 1 \\ -1 & 1 & 0 \end{bmatrix}$. Now $W^{-1} = \begin{bmatrix} 2 & 1 \\ 1 & 1 \end{bmatrix}$. Hence $M_{B,B'} = W^{-1}MQ = \begin{bmatrix} 1 & -1 & 2 \\ 0 & 0 & 1 \end{bmatrix}$.

(ii) Find a general formula for $[(a, b, c)]_B$

by Class notes: $[(a, b, c)]_B = Q^{-1} \begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} -1 & -1 & -1 \\ 1 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} -a - b - c \\ a + b \\ a + c \end{bmatrix}$.

(iii) Find a general formula for $[(c, d)]_{B'}$. By class notes: $[(c, d)]_{B'} = W^{-1} \begin{bmatrix} c \\ d \end{bmatrix} = \begin{bmatrix} 2 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} c \\ d \end{bmatrix} = \begin{bmatrix} 2c + d \\ c + d \end{bmatrix}$.

(iv) Find $[(2, 1, -1)]_B$, $[T(2, 1, -1)]_{B'}$, and $T(2, 1, -1)$

Again, class notes: (a) From (II) $[(2, 1, -1)]_B = Q^{-1} \begin{bmatrix} 2 \\ 1 \\ -1 \end{bmatrix} = \begin{bmatrix} -1 & -1 & -1 \\ 1 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 2 \\ 1 \\ -1 \end{bmatrix} = \begin{bmatrix} -2 \\ 3 \\ 1 \end{bmatrix}$

(b) From class notes: $[T(2, 1, -1)]_{B'} = M_{B,B'} \begin{bmatrix} 2 \\ 1 \\ -1 \end{bmatrix} = \begin{bmatrix} 1 & -1 & 2 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 2 \\ 1 \\ -1 \end{bmatrix} = \begin{bmatrix} -3 \\ 1 \end{bmatrix}$.

(c) From (b) and using B' , $T(2, 1, -1) = -3(1, -1) + 1(-1, 2) = (-4, 5)$.

(v) Write Range T as span

The easiest is to use M from (VII). Stare at M . Do minor row operations. Range = $\text{span}\{(-1, 2), (-2, 2)\}$

(vi) write $Z(T)$ ($\ker(T)$) as span

Staring at M and read the homogenous system, we conclude $Z(T) = \text{span}\{(-1, 0.5, 1)\} = \text{span}\{(-2, 1, 2)\}$.

(vii) Find the standard matrix representation of T .

From (i), MQ is given. Hence $MQ = \begin{bmatrix} 1 & -1 & 1 \\ -1 & 1 & 0 \end{bmatrix}$. Thus, $M = \begin{bmatrix} 1 & -1 & 1 \\ -1 & 1 & 0 \end{bmatrix} Q^{-1} = \begin{bmatrix} -1 & -2 & 0 \\ 2 & 2 & 1 \end{bmatrix}$.

QUESTION 2. Let $T : P_4 \rightarrow P_3$ be a linear transformation over a field F such that $\dim(Z(T)) = 2$ (i.e., $\dim(\ker(T)) = 2$). Convince me that there is a polynomial $f(x) \in P_3$ such that $T(d(x)) \neq f(x)$ for every $d(x) \in P_4$.

Proof. We know $\dim(Z(T)) + \dim(\text{Range}(T)) = 4$. Since $\dim(Z(T)) = 2$, we conclude $\dim(\text{Range}(T)) = 2$. Thus T is not onto. Hence $\text{Range}(T)$ is a proper subspace of P^3 . Thus there is a polynomial $f(x) \notin \text{Range}(T)$. Hence for every $d(x) \in P_4$ we have $T(d(x)) \neq f(x)$.

QUESTION 3. Let $B = \{x^3 + 1, x^3 + x^2 + x + 1\}$ be a basis of a subspace of P_4 over Q . Extend B to a basis of P_4 (over Q). use the techniques I gave you in class. Done. All of you got it right.

QUESTION 4. Let $T : P_4 \rightarrow P_4$ be a linear transformation over R such that $C_T(\alpha) = \alpha^4 - 4\alpha^2$. Find all possible polynomials in P_4 , say $f(x)$, such that $T(f(x)) = -f(x)$

T has only 0 (repeated twice), 2, -2 as eigenvalues. Suppose there is a nonzero polynomial $f(x)$ in P_4 such that $T(f(x)) = -f(x)$. Then we conclude that -1 is an eigenvalue of T . Since -1 is not an eigenvalue of T , we conclude that $T(f(x)) = -f(x)$ if and only if $f(x) = 0$.

QUESTION 5. Let $T : P_4 \rightarrow R^2$ be a linear transformation over R such that $T(f(x)) = (f(1), f(0))$.

1) Find $Z(T)$ ($\text{Ker}(T)$) and write it as span.

Typical question: No one should miss, $Z(T) = \text{span}\{-x^3 + x^2, -x^3 + x\}$.

2) Write $\text{Range}(T)$ as span

Since $\dim(Z(T)) = 2$, then $\dim(\text{Range}(T)) = 2$. Hence $\text{Range}(T) = R^2$ (i.e., T is ONTO). Thus span of any two independent points in $R^2 = \text{Range}(T) = R^2$. For Example, we may say $\text{Range}(T) = \text{span}\{(1, 0), (0, 1)\}$.

QUESTION 6. Let A be a 3×3 matrix over Q with eigenvalues 2, -1. Given $E_2 = \text{span}\{(1, 1, -1), (0, 1, -1)\}$ and $E_{-1} = \text{span}\{(-1, -1, 2)\}$.

1) Find a matrix D , 3×5 , of maximum rank such that $AD - 2D = 0_{3 \times 5}$, where $0_{3 \times 5}$ is the zero-matrix 3×5 .

Note, we need D such that $AD = 2D$. This means: $A \times$ (first column of D) = $2 \times$ (first column of D), and so on, $A \times$ (fifth column of D) = $2 \times$ (fifth column of D). Hence by staring, columns of D must "live" in E_2 . Since $\dim(E_2) = 2$, D will have maximum two independent columns. Thus $\text{Rank}(D) = 2$. So you may take

$$D = \begin{bmatrix} 1 & 0 & 2 & 3 & 0 \\ 1 & 1 & 2 & 3 & 0 \\ -1 & -1 & -2 & -3 & 0 \end{bmatrix}.$$

2) Find $|A|$ and $\text{Trace}(A)$.

by Staring at E_2 and E_{-1} , $C_A(\alpha) = (\alpha - 2)^2(\alpha + 1)$. Eigenvalues are: 2, 2, -1.

Hence $|A| = 2 \times 2 \times (-1) = -4$. $\text{Trace}(A) = 2 + 2 + (-1) = 3$.

QUESTION 7. Let $T : P_2 \rightarrow P_2$ be a linear transformation over R such that $C_T(\alpha) = \alpha^2 - 4$.

1) Let $L : P_2 \rightarrow P_2$ be a linear transformation over R such that $L(f(x)) = T^2(f(x)) + 4T(f(x)) + f(x)$. Find $C_L(\alpha)$

Eigenvalues of T are 2, -2. Thus exist nonzero polynomials $d(x), w(x) \in P_2$ such that $T(d(x)) = 2d(x)$ and $T(w(x)) = -2w(x)$. Thus $L(d(x)) = T^2(d(x)) + 4T(d(x)) + d(x) = 4d(x) + 8d(x) + d(x) = 13d(x)$. Hence 13 is an eigenvalue of L .

$L(w(x)) = T^2(w(x)) + 4T(w(x)) + w(x) = 4w(x) - 8w(x) + w(x) = -3w(x)$. Thus -3 is an eigenvalue of L .

Hence $C_L(\alpha) = (\alpha - 13)(\alpha + 3)$.

2) For every $f(x) \in P_2$, find $T^4(f(x))$

Clearly, $P_2 = \text{span}\{d(x), w(x)\}$ ($\mathbf{d(x)}, \mathbf{w(x)}$ as in (1) above). Let $f(x) \in P_2$. Then $f(x) = ad(x) + bw(x)$ for some $a, b \in R$.

Thus $T^4(f(x)) = T^4(ad(x) + bw(x)) = aT^4(d(x)) + bT^4(w(x)) = 16ad(x) + 16bw(x) = 16(ad(x) + bw(x)) = 16f(x)$.

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